

*Application for*  
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*Of*

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**NETWORK SYSTEM**

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- 1 -

## NETWORK SYSTEM

### BACKGROUND OF THE INVENTION

The present invention generally relates to network systems for remotely controlling a plurality of electric apparatus, and particularly to a network  
5 system suitable for use with home appliances.

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Recently, most of the electric apparatuses (electrical appliances) used at home have functions for remote controlling so that they can be remotely controlled. However, in general, a particular remote  
10 controller is provided for each electric appliance. Therefore, the number of remote controllers is so increased as to be troublesome in their storage management, and that a lot of trouble is taken when a specific one is searched out from many remote control-  
15 lers.

Thus, a system has been proposed that enables a single remote controller to be used in common to a plurality of electric appliances.

One example is disclosed in, for example,  
20 JP-A-11-098028 "Remote Controller Transmitter". In this document, one common remote controller (remote controller transmitter) is provided to use for a plurality of electric appliances that employ the same remote controlling codes (here, ceiling lamps). This  
25 remote controller emits infrared light and visible

The infrared light to be emitted from the remote controller generally has a certain degree of

5 spread. Thus, when the remote controller is only  
loosely directed toward an electric appliance to be  
controlled, this appliance can receive the infrared  
light. When the infrared light is transmitted over a  
certain degree of spread, however, the infrared-  
10 sensitive portions of more than at least two of a  
plurality of ceiling lamps, if installed relatively  
close to each other in a room, could receive the  
infrared light and thus be controlled at a time.  
Therefore, in this background art, the spread of the  
15 infrared light from the remote controller is restricted  
to be narrow (i.e., a directivity is given to the  
infrared), and at the same time the visible light that  
is also given a directivity (here, visible laser light)  
is emitted from the remote controller along the same  
20 light axis as the infrared in order that the appliance  
irradiated with the nonvisible infrared light can be  
found by the user.

The above conventional example uses the remote controller for a plurality of electric appliances sensitive to the same remote controlling codes. Another example disclosed in, for example, JP-A-11-136776 is a system capable of using a single remote controller common to a plurality of electric appliances

that employ different remote controlling codes.

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In this system, the remote controlling codes for the electric appliances are previously stored in the built-in memory of the remote controller, and one of the codes is selected for the desired appliance by operating the key input portion of the remote controller while the contents are being displayed on this remote controller. The remote controlling code for the desired appliance to be controlled is thus read from the memory, and the infrared light modulated with this remote controlling code is emitted. Consequently, after the above operations, the user directs this remote controller toward the infrared-sensitive portion of the appliance to be controlled, thereby controlling this apparatus.

Moreover, JP-A-09-238385 discloses a technique in which GUI (Graphic User Interface) of apparatus connected in a network manner is displayed on a screen such as TV screen, and controlled by a remote controller. In addition, JP-A-2001-036976 describes a technique in which operation buttons (GUI) are displayed on a remote controller, and selectively operated to control one of the apparatus connected in a network manner.

## 25 SUMMARY OF THE INVENTION

In the examples of JP-A-11-098028, and JP-A-11-136776, since a single remote controller can be used

common to a plurality of electric appliances, it is easy to keep and manage the remote controller, and there is not such trouble as to select a remote controller for each appliance.

- 5           However, even in the any ones of the above conventional examples, the infrared light is required to be emitted toward the infrared-sensitive portion of the appliance to be controlled, and thus the user needs to at least direct the remote controller to the
- 10 infrared-sensitive portion of the appliance to be controlled. Particularly when operating the remote controller near the appliance to be controlled, the user cannot find where the infrared is irradiated to since the infrared emitted from the remote controller
- 15 has a certain degree of spread and is invisible, and thus the user must appreciably precisely direct the remote controller to the infrared-sensitive portion. Therefore, this operability becomes a problem for the general user.
- 20           In the example of JP-A-11-098028 in which the visible light is irradiated along the same light axis as the infrared to make the user find the position where the infrared is irradiated, use of the visible light only for the user to find the irradiated position
- 25 other than the infrared light for the control causes visible-light emitting means to be added to the remote controller, thus making it complicated and large-sized in its construction, and expensive.

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controlable range within the field is set to include the objects to be controlled and which detects only light of a particular wavelength region, a commander for generating electromagnetic waves toward a given position within the field of view or within the controlable range to form a light pointer of the particular wavelength range at the position irradiated with the electromagnetic waves, and capable of remote controlling, and a control unit that processes an output signal from the video camera to detect any one or ones, indicated by the pointer, of the objects to be controlled, receives from the commander an operation signal associated with the remote controlling on the indicated object, and supplies a control signal according to the operation signal through a network to the object indicated by the pointer, so that the object indicated by the pointer can be remotely controlled by the commander.

There is also provided a network system according to the above system, wherein, for each of the electric appliances, an apparatus recognition range is set to define the range of the appliance within the field of view of the video camera, and the control unit, when one of the apparatus recognition ranges is selected by the pointer, detects the appliance associated with the apparatus recognition range indicated by the pointer, and supplies the control signal to the detected appliance.

5 increase or decrease its brightness by moving the  
pointer within the apparatus recognition range of the  
lamp made in the on-state.

10 project an image on a region other than the apparatus  
recognition ranges that are included within the field  
of view or the controllable ranges, the control unit  
controls the air conditioner to be switched on and off  
each time the air conditioner is designated by the  
15 pointer, and the control unit controls the projector by  
designating the air conditioner by the pointer and by  
proper remote control operations on the commander, to  
display an operation panel for the air conditioner  
within the field of view or within the controllable  
20 range so that the air conditioner can be remotely  
controlled on the operation panel.

25 apparatus recognition ranges within the field of view  
or the controllable ranges, the control unit controls  
the television set to be switched on and off each time  
the television set is designated by the pointer, and



the control unit controls the projector by use of the pointer to indicate the television set and by use of the commander to make a certain remote controlling operation so that an operation panel for the television set can be displayed on a region within the field of view or the controllable range and that the television set can thus be remotely controlled on the operation panel.

Moreover, where the electric appliances are a television set and a refrigerator, the control unit registers the refrigerator to be in a designated state by specifying the refrigerator by the pointer, and under the condition that the specification of the refrigerator is registered, the control unit controls the television set by use of the pointer to designate the television set, and by use of the commander to make a certain remote controlling operation, so that the state in which foods are placed in the refrigerator can be displayed on the television set.

20 Also, where the electric appliances are a  
television set, a refrigerator and an electronic oven,  
the control unit registers the refrigerator and the  
electronic oven to be in a registered state by use of  
the pointer to designate the refrigerator and the  
25 electronic oven, and under the condition that the  
designation of the refrigerator and the electronic oven  
is registered, the control unit controls the television  
set by use of pointer to designate the television set

and by use of the commander to make a certain remote controlling operation, so that information of possible recipes using foods placed in the refrigerator is displayed on the television set.

5                    Additionally, where the electric appliances  
are a television set, a refrigerator and an electronic  
oven; the control unit registers the refrigerator and  
the electronic oven to be in a designated state by  
designating the refrigerator and the electronic oven  
10 by use of pointer to designate the refrigerator and  
the electronic oven; under the condition that the  
refrigerator and the electronic oven are designated,  
the control unit controls the television set by use of  
pointer to designate the television set and by use of  
15 the commander to make a certain remote controlling  
operation, so that the state in which foods are placed  
in the refrigerator is displayed on the television set;  
and under the condition that the state in which foods  
are placed in the refrigerator is displayed on the  
20 television set, the control unit controls the televi-  
sion set by registering the electronic oven, so that  
information of possible recipes using foods placed in  
the refrigerator can be displayed on the television  
set.

25           Also, a projector is additionally provided to project an image on a region other than the apparatus recognition ranges within the field of view or the controllable ranges, and by depicting a frame by the



FIG. 9 is a flowchart of a main routine involved in the operation of the remote controller in the embodiment of FIG. 1.

FIGS. 11A and 11B are diagrams showing examples of user's operation for controlling (1) of step 107 in FIG. 9.

FIGS. 13A through 13D are diagrams showing the user's operation for the dimmer controlling (2) of step 107 in FIG. 9.

FIG. 15 is a flowchart of the on-and off-controlling (3) of an air conditioner in step 107 of FIG. 9.

FIG. 17 is a flowchart of user's operation for setting control of the air conditioner in FIG. 13.

FIG. 18 is a flowchart of the on, off controlling (5) of TV set in step 107 of FIG. 9.

FIG. 19 is a flowchart of the information displaying control (6) of TV set in step 107 of FIG. 9.

FIG. 20 is a flowchart of designate control (7) of refrigerator in step 107 of FIG. 9.

5           FIG. 21 is a flowchart of designate control (8) of electronic oven in step 107 of FIG. 9.

FIGS. 22A and 22B are diagrams showing user's operation to display on TV set the information of the refrigerator by the information displaying control (6)  
10 of FIG. 19.

FIGS 23A, 23B and 23C are diagrams showing examples of images displayed on TV set under the control operation of FIG. 19.

FIGS. 24A, 24B and 24C are diagrams showing  
15 examples of user's operation to display on TV set the information about cooking of refrigerated foods under the control (6) of FIG. 19 in step 107.

FIG. 25 is a flowchart of information displaying control (9) of step 107 in FIG. 9.

20           FIGS. 26A, 26B and 26C are diagrams showing examples of information displayed on the wall surface under the control operation of FIG. 25.

FIGS. 27A and 27B are diagrams showing examples of user's operation for the control operation  
25 of FIG. 25.

#### DESCRIPTION OF THE EMBODIMENTS

An embodiment of the invention will be

described with reference to the drawings.

FIG. 1 is a diagram showing one embodiment of a network system according to the invention.

Referring to FIG. 1, there are shown a video camera 1,  
5 a projector 2, a control box 3, an antenna 3a, a remote  
controller 4, a laser beam 5, a controlable range 6, a  
pointer 7, a refrigerator 8, a television receiver 9  
(hereafter, referred to as TV set), an air conditioner  
10, an lamp 11 and signal lines 12.

10 As in FIG. 1, electric apparatus to be remote  
controlled in this embodiment are installed within a  
room. These apparatus are, as illustrated, electric  
appliances such as the refrigerator 8, TV set 9, air  
conditioner 10, lamp 11 and electronic oven (not  
15 shown). These electric appliances are generally  
arranged near the wall within a room. Here, for the  
sake of convenience of explanation, it is assumed that  
these electric appliances 8 ~ 11 are placed on the same  
wall side within this room. In addition, the video  
20 camera 1 and projector 2 are installed with this room.  
This video camera 1 is fixedly placed so that its field  
of view can be set to provide the controlable range 6  
that includes all these electric appliances 8 ~ 11.  
The projector 2 projects a predetermined image within  
25 this controlable range 6.

FIG. 2 schematically shows a specific  
example of the controlable range 6. The entire scene  
illustrated depicts the look of the room within the

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5 to be controlled can be included at least within this  
field of view. The controlable range 6 is also set to  
include all these appliances 8 ~ 11, and 13.

10 of the field view of video camera 1 may be assumed to  
be the controlable range 6.

In this embodiment, as illustrated in FIG. 1, the remote controller 4 is used to generate a beam of visible laser light for remotely controlling each one of the appliances 8 ~ 11 to be controlled.

The remote controller 4 is operated by the user to emit a beam of visible laser light 5. When this laser beam 5 is irradiated over the controllable range 6, the irradiated point appears as the pointer 7 on any one of the wall surface (not shown) and the surfaces of appliances 8 ~ 11 within the controllable range, and this pointer 7 is picked up by the video camera 1.

The control box 3 is connected to the video camera 1, projector 2 and appliances 8 ~ 11 by way of signal lines 12, and supplied with the output from the video camera 1, and it controls the projector 2 and appliances 8 ~ 11. The control box 3 has the receiving

antenna 3a, which can receive an radio information signal transmitted from the remote controller 4.

FIG. 3 is a block diagram showing the functions of each element given in FIG. 1 and the connection thereof. Referring to FIG. 3, there are shown a control portion 3A, a receiving portion 3B, a storage portion 3C, a network connection portion 3D, an operation portion 4A, a laser pointer 4B, a radio transmitter 4C, a motor-driven universal head (camera platform) 14, A/V equipment 15a, a home appliance 15b, and an illuminator 15c. In FIG. 3, like elements corresponding to those in FIG. 1 are identified by the same reference numerals.

The video camera 1 and projector 2 in FIG. 3 are fixed on the motor-driven camera platform 14. This motor-driven camera platform 14 is used to adjust the field of view when the video camera 1 and projector 2 are installed within a room. The control box 3 includes the control portion 3A, receiving portion 3B, storage portion 3C and so on. The control portion 3A is connected through the network connection portion 3D to electric appliances, i.e., the A/V equipment such as TV set 9 and stereo components shown in FIG. 1, the home appliance 15b such as air conditioner 10, refrigerator 8, electronic oven or electric washer shown in FIG. 1, and the illuminator 15c such as lamp 11 shown in FIG. 1. The receiving portion 3B of the control box 3 receives via the antenna 3a (see FIG. 1)



the signal transmitted from the remote controller 4.  
The control portion 3A responds to the output signal  
from the video camera 1 and to the received signal from  
the receiving portion 3B to control the projector 2 and  
5 each of the electric appliances 15a ~ 15c to turn on  
and off or to make other controlling operations.

The remote controller 4 has the operation  
portion 4A, laser pointer 4B and radio transmitter 4C.  
A specific example of the remote controller 4 will be  
10 described with reference to FIGS. 4A ~4E. FIG. 4A is a  
top view of the remote controller 4, FIG. 4B a side  
view thereof, FIG. 4C a front view thereof, FIG. 4D a  
cross-sectional view thereof taken along a line B-B in  
FIG. 4B, and FIG. 4E a longitudinal sectional view  
15 thereof taken along a line A-A in FIG. 4A. In these  
figures, 4a and 4b represent operation buttons (these  
are hereafter called A-button, and B-button, respec-  
tively), 4c a window, 4d<sub>1</sub> and 4d<sub>2</sub> laser generators, 4e<sub>1</sub>  
and 4e<sub>2</sub> hologram filters, 4f a wireless board, and 4g a  
20 battery. In FIGS. 4A ~4E, like elements corresponding  
to those in FIG. 3 are identified by the same reference  
numerals.

In FIGS. 4A ~4E, the top of the housing of  
the remote controller 4 has the operation portion 4A  
25 on which the A-button 4a and B-button 4b are provided,  
and the front side of the housing has the window 4c  
provided which allows each laser beam to pass there-  
through.

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The inside of the housing of the remote controller has the laser pointer 4B, radio transmitter 4C and battery 4g as a power supply as shown in FIGS. 4D and 4E. The laser pointer 4B has two laser generators 4d<sub>1</sub>, 4d<sub>2</sub>, and hologram filters 4e<sub>1</sub>, 4e<sub>2</sub> to oppose the laser generators 4d<sub>1</sub>, 4d<sub>2</sub>. The hologram filters change the visual shape of the pointer of the laser beam passing therethrough. The laser generator 4d<sub>1</sub>, hologram filter 4e<sub>1</sub>, and laser generator 4d<sub>2</sub>, hologram 4e<sub>2</sub> constitute laser pointers, respectively. Thus, this remote controller 4 has two laser pointers provided. Here, for example, the hologram filter 4e<sub>1</sub> forms the pointer 7 of shape •, and the hologram filter 4e<sub>2</sub> forms the pointer 7 of shape ☆. Since these hologram filters 4e<sub>1</sub>, 4e<sub>2</sub> diffuse the laser beams, the laser beams, if coming into view, do not affect user's eyes, or they are safe.

In addition, the radio transmitter 4C has the wireless board 4f on which various types of processing circuits, transmission circuits, and a transmitting antenna (not shown) are provided.

The A-button 4a and B-button 4b are constructed to be pushed twice: the first-step operation called half-push operation, and further-push operation, or the second-step operation called full-push operation. When the A-button 4a is half-pushed, the laser generator 4d<sub>1</sub> emits a visible laser beam. When the B-button 4b is half-pushed, the laser generator 4d<sub>2</sub>

emits a visible laser beam. The visible laser beam emitted from the laser generator  $4d_1$  is passed through the hologram filter  $4e_1$ , and irradiated to the outside through the window  $4c$ . The visible laser beam emitted from the laser generator  $4d_2$  is passed through the hologram filter  $4e_2$ , and irradiated to the outside through the window  $4c$ . Since the laser beams generated when the A-button  $4a$  and B-button  $4b$  are operated are passed through the different hologram filters, the shapes of pointers  $7$  are different. Thus, from the shapes of the pointers  $7$ , the user can easily decide that either A-button  $4a$  or B-button  $4b$  has been pushed. When the A-button  $4a$ , B-button  $4b$  is full-pushed, the radio transmitter  $4c$  transmits a signal corresponding to the full-pushed button. At this time, or when the A-button  $4a$ , B-button  $4b$  is full-pushed, a visible laser beam is of course generated from the laser generator  $4d_1, 4d_2$ .

Fig. 5 is a block diagram showing the flow of signals in this embodiment. Referring to FIG. 5, there are shown a band-pass filter  $1a$ , a band-cut filter  $2a$ , radio transmitters  $4c_1, 4c_2$ , USB (Universal Serial Bus) keyboard (modified)  $3b$ , a control-purpose personal computer (personal computer)  $3c$ , relays  $16a \sim 16d$  keyboard (modified)  $17a, 17b$ , GUI (Graphic User Interface)-purpose personal computers  $18a, 18b$ , and a scan converter  $19$ . In FIG. 5, like elements corresponding to those in the previous figures are

identified by the same reference numerals, and will not described.

As illustrated, the remote controller 4 has radio transmitters  $4C_1$ ,  $4C_2$  provided for A-button 4a, B-  
5 button 4b, respectively. When the A-button 4a and B-button 4b are full-pushed, the radio transmitters  $4C_1$ ,  $4C_2$  emit different signals. The signals transmitted from the radio transmitters  $4C_1$ ,  $4C_2$  are supplied to the control box 3, where they are received by the antenna  
10 3a, and fed to the receiving portion 3B. The signals from the receiving portion 3B are fed through the USB keyboard 3b to the control-purpose personal computer 3c. The control-purpose computer 3c includes the control portion 3A, storage portion 3C and network  
15 connection portion 3D shown in FIG. 3.

The video camera 1 has the band-pass filter 1a detachably mounted in order that only the wavelength region of the visible laser beam emitted from the remote controller 4 can be substantially passed there-  
20 through. When this band-pass filter 1a is mounted, the visible laser beam emitted from the remote controller 4 and reflected from the surfaces of electric appliances or the surfaces of the walls is incident to the imaging surface of the video camera 1 as shown in FIG. 1. The  
25 video signal produced from the video camera 1 is supplied to the control portion 3A of the control box 3.

The personal computer 3c of the control box 3

20 Referring to FIGS. 1 ~ 5, the specification  
of an appliance to be controlled is made by detecting  
the pointer 7 of the visible laser beam 5 the remote  
controller 4 emits from the output of the video camera  
1. Thus, when the specification is made (i.e., when  
25 this embodiment is actually operated), as shown in FIG.  
5, the band-pass filter 1a of the video camera 1 is  
mounted on a camera lens not shown so that only the  
laser beam 5 is incident to the imaging surface, or

that the other images than the field of view of the video camera 1 can be cut off, or removed. Then, the personal computer 3c of the control box 3 detects the image of the spot of laser beam 5 from the video signal the video camera 1 has produced, and detects where this beam spot position is located within the range 6 to be controlled as shown in FIG. 2, i.e., the coordinates of this beam spot on the coordinate system set as the controllable range 6. From the results from the detection, it is decided which one of the electric appliances 8 ~ 11, 13 corresponds to the coordinates within the controllable range 6, thereby making designation of a particular appliance selected by the laser beam.

To this end, the scene within the field of view of the video camera 1 as shown in FIG. 6A (the same as in FIG. 2) is previously converted as in FIG. 6B, i.e., the controllable range 6 is expressed by a X-Y coordinate system of field view 20 of video camera 1, and the regions (hereafter, called apparatus recognition range) of the electric appliances 8 ~ 11, 13 to be controlled are expressed by a x-y coordinate system within the controllable range 6. Additionally, this information is previously stored in the storage portion 3c (see FIG. 3) of the control box 3. In FIG. 6B,  $AR_8$  is the apparatus recognition range set for the refrigerator 8, and similarly  $AR_9$ ,  $AR_{10}$ ,  $AR_{11}$ ,  $AR_{13}$  the apparatus recognition ranges set for TV set 9, air

conditioner 10, lamp 11, electronic oven 13. Therefore, when the pointer 7 detected by the video camera 1 points to the refrigerator 8, the image position (hereafter, called point position) of the pointer 7 within the controllable range 6 in FIG. 6B is included within the apparatus recognition range  $AR_8$  of the refrigerator 8. Thus, the personal computer 3c decides that this refrigerator 8 is designated by the laser beam (hereafter, referred to as "specified by pointer"). Other electric appliances are also specified as described above.

While the apparatus recognition range includes the range that the appliance actually occupies, and is shown in a rectangular shape that is slightly larger than this range, it is not limited to this shape, but may be shown by the range itself that the electric appliance actually occupies, or shown in other shapes.

The setting of the controllable range 6 within the field view of video camera 1 and the apparatus recognition range of each appliance within this controllable range 6 can be made as described later by the operation of remote controller 4 and operation of the control box 3, or by use of a dedicated purpose apparatus (personal computer). In this case, the band-pass filter 1a is removed from the camera lens, and the video signal produced from the video camera 1 is supplied to the personal computer, and processed while

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viewing the displayed image. Data showing the positional relation of the apparatus recognition range of each electric appliance to the field view 20 of video camera 1 shown in FIG. 6B (this data is hereafter referred to as arrangement information of apparatus recognition range), obtained by this operation, is supplied to the control box 3 and stored in the storage portion 3c.

FIG. 7 shows the functions of each of the control portion 3A and storage portion 3C of the personal computer 3c shown in FIG. 5. In FIG. 7, 3A<sub>1</sub> represents a pointer extractor, 3A<sub>2</sub> a pointer position calculator, 3A<sub>3</sub> an operation content discriminator, 3A<sub>4</sub> a control signal decider, 3A<sub>5</sub> a control code decider, 3C<sub>1</sub> a calibrator, 3C<sub>2</sub> an apparatus recognition range database, 3C<sub>3</sub> an apparatus status database, and 3C<sub>4</sub> an apparatus control database.

In FIG. 7, the storage portion 3C has a conversion table stored for coordinates conversion by which the variation of field view of video camera 1 is compensated for, i.e., for converting the camera coordinate system to a correct coordinate system (system frame of reference), as the calibration data 3C<sub>1</sub>. When a camera image is obtained from the video camera 1 with the band-pass filter 1a mounted on the lens, the pointer extractor 3A<sub>1</sub> of the control portion 3A extracts the image of the pointer 7 (see FIG. 1) from the obtained image and determined in its position



In the storage portion 3C is stored the arrangement information of apparatus recognition ranges in which the apparatus recognition ranges  $AR_8 \sim AR_{11}$ ,  $AR_{13}$ , shown within the controllable range 6 in FIG. 6B are expressed by x-y coordinate as the apparatus recognition range database  $3C_2$ . The operation content discriminator  $3A_3$  of the control portion 3A decides which apparatus recognition range the pointer position expressed by the system frame of reference (x-y coordinate system) obtained by the pointer position calculator  $3A_2$  is included in on the basis of this apparatus recognition range database  $3C_2$ . Thus, the electric appliance specified by the pointer 7 generated when the user operates the remote controller 4 as shown in FIG. 1 can be found.

20 As illustrated in FIG. 7, in the storage  
portion 3C is also stored status parameters that  
indicate the on/off status of each appliance 8 ~ 11,  
13 within the controllable range 6, and other status  
settings as apparatus status database 3C<sub>3</sub>. FIG. 8 shows  
25 a specific example of the apparatus status database 3C<sub>3</sub>.  
Here, Li, Ai and Te represent status parameters showing  
the on/off status of the lamp 11, air conditioner 10  
and TV set 9, and Re and Mi denote status parameters

indicating if the refrigerator 8 and electronic oven 13 are respectively specified. The designation of electronic oven 13 and refrigerator 8 means that the internal states of electronic oven 13 and refrigerator 8 are specified in order to be displayed on the TV set 9 (in this case, the TV set 9 is also required to specify for that designation). If the electronic oven 13, for example, is designated as described above, the internal state of this electronic oven 13 is displayed on the TV set 9.

Thus, when the pointer position on the x-y coordinate system is detected, and when the signal generated from the remote controller 4 by the button operation is received by the receiving portion 3B (see FIG. 3), the operation content discriminator 3A<sub>3</sub> discriminates the contents of the operation of remote controller 4 from this received signal and the detected pointer position, and the result of the discrimination is supplied to the control signal decider 3A<sub>4</sub>.

Thus, the control signal decider 3A<sub>4</sub> detects the state of the electric appliance of the apparatus recognition range found by the operation content discriminator 3A<sub>3</sub> by use of the apparatus status database 3C<sub>3</sub>, and decides the control signal for this appliance from the detection result and the found operation content of remote controller 4. If this received signal is, for example, a command signal to make the air conditioner 10 in the on-state, the

control signal decider  $3A_4$  detects, from the apparatus  
status database  $3C_3$ , that this received signal is a  
signal of the status parameter of air conditioner 10,  
and that this air conditioner 10 is now in the off-  
5 state, and decides the control signal for turning air  
conditioner 10 on.

In the storage 3C is stored apparatus control  
database  $3C_4$  with codes (control codes) set according to  
the types of control for each electric appliance. The  
10 control code decider  $3A_5$  converts the control signal  
decided by the control signal decider  $3A_4$  to an  
associated control code on the basis of the apparatus  
control database  $3C_4$ , and supplies it to an electric  
appliance as a connected apparatus to be controlled.

15 Next, a description will be made of the  
operation of this embodiment associated with the  
operation of the remote controller 4.

FIG. 9 is a flowchart of the main routine for  
that operation.

20 Referring to FIGS. 5 and 9, if a main switch,  
not shown, that is provided at the entrance of a room  
in which the system according to this embodiment is  
installed, is turned on, the control box 3 and video  
camera 1 are powered to be operative (step 100).

25 The personal computer 3c of the control box 3  
initialize the apparatus status database  $3C_3$  (see FIG.  
7) in the storage portion 3C to make the status  
parameters of electric appliances 8 ~ 11, 13 off, and

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turns the relays 16a ~ 16d off, thereby causing these electric appliances 8 ~ 11, 13 to be in the off-state so that the electronic oven 13, refrigerator 8, and so on are not designated (step 101).

5           Then, it is decided if calibration is necessary (step 102). If it is not necessary, the routine goes to step 104. If it is necessary, calibration is made (step 103), and the routine goes to step 104.

10           The information of if calibration is necessary is previously set in the personal computer 3C. If it is set, after the initialization in step 101, the routine surely goes to step 103. If it is not set, the routine does not go to step 103, but to step 104.

15           FIG. 10 is a flowchart of a specific example of the processing in step 103.

          This calibration operation includes the correction necessary when the field of view of video camera 1 has been changed (field-view calibration), and the setting of apparatus recognition ranges.

20           In FIG. 10A, it is first decided if the field-view calibration is necessary (step 200). To this end, a reference frame 21 of the same color as the visible beam from the remote controller 4 is projected by projector 2 as shown in FIG. 10B. This scene is  
25           picked up by the video camera 1 with the band-pass filter 1a mounted on the lens system, and the video signal from the camera is supplied to the personal computer 3c of the control box 3. The personal

computer 3c extracts this reference frame 21 from this video signal, and determines the position of the reference frame 21 in the field view 20 of the video camera 1. Since the correct positional information of the reference frame 21 in the field view 20 is already stored in the storage portion 3C of the control box 3, the position of the reference frame 21 obtained from the video signal is compared with this positional information. As illustrated in FIG. 10A, if both positions are equal, it is decided that the field view calibration is not necessary (step 200), and the routine goes to step 202. If both positions are not equal, it is decided that the field view calibration is necessary (step 200), and the routine goes to step 201. In this step 201, positional correction information is calculated in order for the obtained position to be coincident with the positional information of the reference frame 21 stored in the control box 3, and used to correct the calibrator data  $3C_1$ , and hence the conversion table in the storage portion 3C.

After the field view calibration is finished, it is decided if the apparatus recognition range setting is necessary (step 202). When a new appliance is added or when any one of the appliances to be controlled is moved, the apparatus recognition range of this appliance is set (step 203).

If there is not any newly installed appliance, the routine goes to step 204. If, for

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example, the electronic oven 13 is newly added, and desired to be capable of being remotely controlled by the user using this system, the user operates for this purpose by using the USB keyboard 3b (see FIG. 5) of the control box 3 and the remote controller 4. At this time, as illustrated in FIG. 10A, the routine goes from step 204 back to step 203 where the apparatus recognition range for this electronic oven 13 can be set.

That is, in the control box 3, the USB keyboard 3b is operated first to set the setting mode of the apparatus recognition range, and the remote controller 4 is operated so that the laser beam 5 depicts a locus around the electronic oven 13 to include it. This locus is imaged by the video camera 1, and the personal computer 3c extracts the image of the locus from the output from this video camera 1. The rectangular region substantially corresponding to the locus is stored as the apparatus decision region  $AR_{13}$  of this electronic oven 13 in the storage portion 3C so that it can be additionally registered in the apparatus recognition range database  $3C_2$  as described with reference to FIG. 7. Thus, the apparatus recognition range  $AR_{13}$  for electronic oven 13 is set as shown in FIG. 10C. In addition, the control signal for remotely controlling this electronic oven 13, and the relation between the control signal and the operation of remote controller 4 are entered by use of, for

10082107-022602

example, USB keyboard 3b, and the input information is registered in the storage portion 3C as described with reference to FIG. 7. When this registration is finished, operation for end of setting is performed by  
5 USB keyboard 3b so that the setting of the apparatus recognition range for this electronic oven 13 (step 203 in FIG. 10A) is finished, and the routine goes to step 204.

Although the method for setting the apparatus  
10 recognition range for each appliance by using the dedicated personal computer for the setting of apparatus recognition range has been described so far, the apparatus recognition range of each appliance 8 ~ 11 may be set by the operation of remote controller 4 and  
15 control box 3.

Turning back to FIG. 9, in step 104, the control box 3 is maintained active to acquire the video signal from the video camera 1 unless the above-mentioned main switch is turned off to stop the system.  
20 When the pointer 7 is detected in its position (i.e., when any one of appliances 8 ~ 11, 13 is indicated by pointer 7: step 105), it is decided if there is a received signal from the remote controller 4 with the A-and B-buttons 4a, 4b full-pushed (step 106). When  
25 the received signal is obtained, the routine goes to step 107.

In step 107, the following operations are performed according to the position of pointer 7 within

the controllable range 6, and the way (single click and double click) of full-pushing the A-, and B-buttons 4a, 4b on the remote controller 4.

[Remote controlling of lamp 11]

- 5           ① of Step 107 in FIG. 9; i.e., the case when the pointer 7 is within the apparatus recognition range  $AR_{11}$  (FIG. 6B) of lamp 11, and when the A-button 4a is single-clicked on remote controller 4:

10           This case corresponds to the operation shown in FIGS. 11A and 11B. At this time, controlling is made according to the flowchart of FIG. 12.

15           That is, as shown in FIG. 11A, the user half-pushes the A-button 4a with the remote controller 4 directed to the lamp 11 so that the pointer 7 is applied directly to the lamp 11 or its neighbor, and as shown in FIG. 11B the A-button 4a of remote controller 4 is once full-pushed, or single-clicked. When the personal computer 3c of control box 3 detects from the output from the video camera 1 that this pointer 7 is  
20           within the recognition range  $AR_{11}$  of lamp 11, the status parameter  $Li$  of lamp 11 is checked on the basis of the apparatus status database  $3C_3$  of storage portion 3C (FIG. 7) as shown in FIG. 12 (step 300). If  $Li = ON$ , the lamp 11 is decided to be now switched on. Then, a  
25           control signal for switching the lamp 11 off is applied to it, energizing the relay 16b (see FIG. 5), thereby extinguishing the lamp 11. Moreover, the status parameter  $Li$  is turned off on the apparatus status



database 3C<sub>3</sub> (step 301). If the lamp 11 is now off (Li  $\neq$  ON in step 300), similarly the lamp 11 is switched on, and the status parameter Li on the apparatus status database 3C<sub>3</sub> is turned on (step 302).

5           Thus, each time the A-button 4a of remote controller 4 is single-clicked under the condition that the lamp 11 is designated by the pointer 7, the lamp 11 is repeatedly switched on and off.

10           ② of step 107 in FIG. 9; i.e., the case when the pointer 7 is within the apparatus recognition range AR<sub>11</sub> (FIG. 6B) of lamp 11, and the A-button 4a is double clicked on the remote controller 4:

15           This case corresponds to the operation shown in FIGS. 13A ~ 13D. In this case, controlling is made according to the flowchart of FIG. 14.

20           That is, the user half-pushes the A-button 4a with the remote controller 4 directed to the lamp 11 so that the pointer 7 is applied directly to the lamp 11 or to its vicinity, and the A-button 4a of remote controller 4 is double clicked as shown in FIG. 13A. At this time, the personal computer 3c detects the coordinates (x0, y0) of the pointer 7 within the controllable range 6, and the coordinates (x0, y0) of the pointer 7, if being within the apparatus recognition range AR<sub>11</sub> of lamp 11, is stored as a reference position in the storage portion 3C (step 400 in FIG. 14). Then, if the status parameter Li of lamp 11 on the apparatus status database 3C<sub>3</sub> (see FIG. 7) is ON

10082107.022602

(i.e., if the lamp 11 is on: step 401 in FIG. 14), the routine goes to step 403 where the processing enters into dimming mode. If the status parameter Li is off (i.e., if the lamp 11 is off: step 401 in FIG. 14), the  
5 personal computer 3c energizes the relay 16b (see FIG. 5), thus switching the lamp 11 on (step 402 in FIG. 14), and the routine goes to step 403.

In the dimming mode (step 403 in FIG. 14), the personal computer 3c observes the change of the  
10 height of pointer 7 that is imaged by the video camera 1. If, now, the user changes, as illustrated in FIG. 13B, the direction of remote controller 4 to be turned more upward than when the A-button 4a is previously double clicked so that the pointer 7 is raised in its  
15 position to be higher than the reference position ( $x_0$ ,  $y_0$ ) that is obtained when the A-button 4a is double clicked, the personal computer 3c detects this change (step 404 in FIG. 14), controlling the brightness of lamp 11 to be raised one rank. By repeatedly shaking  
20 the pointer 7 at a higher point than this reference position ( $x_0$ ,  $y_0$ ) in the height direction, the brightness can be increased by each shake at a constant rate until the maximum (step 405 in FIG. 14). If, as shown in FIG. 13C, the pointer 7 is repeatedly shaken  
25 in the height direction at a lower point than the reference position ( $x_0$ ,  $y_0$ ) (step 404 in FIG. 14) contrary to the above case, the brightness can be decreased by each shake at a constant rate until the

minimum (step 406 in FIG. 14).

If the pointer 7 is lighted for more than two seconds (step 407 in FIG. 14), the routine goes back to step 403 where the dimming mode is again performed. If the pointer 7 continues the off-state for more than two seconds as shown in FIG. 13D, the processing goes back to step 104 in FIG. 9.

In the above dimming mode, the dimmer control signal is generated on the basis of the wireless portion button operation of A-button 4a in the operation content discriminator 3A<sub>3</sub> and the positional change of pointer 7 detected by the pointer position calculator 3A<sub>2</sub> as illustrated in FIG. 7.

Thus, the user can set the on-and off-state and dimming mode (brightness) of lamp 11 while sitting on a sofa. In addition, since this setting can be performed by directing the visible laser beam to around the lamp 11 to be controlled, the user can operate easily and without mistake.

[Remote controlling of air conditioner 10]

③ of step 107 in FIG. 9; i.e., the case when the pointer 7 is within the apparatus recognition range AR<sub>10</sub> (FIG. 6B) of air conditioner 10, and when the A-button 4a is single-clicked on the remote controller 4:

This case corresponds to the control according to the flowchart shown in FIG. 15.

That is, as shown in FIG. 16A, the user half-pushes the A-button 4a with the remote controller 4

directed to the air conditioner 10 so that the laser beam is applied as pointer 7 to the air conditioner 10, and the A-button 4a of remote controller 4 is once full-pushed, or single-clicked. When the personal

5 computer 3c of the control box 3 detects from the output from the video camera 1 that the pointer 7 is within the apparatus recognition range  $AR_{10}$  of air conditioner 10, it checks the status parameter  $A_i$  of air conditioner 10 on the basis of the apparatus status

10 database  $3C_3$  of storage portion 3C (FIG. 7) as shown in FIG. 15 (step 500). If  $A_i = ON$ , the air conditioner 10 is decided to be now ON, and a control signal is transmitted to the air conditioner 10, energizing the relay 16a (FIG. 15) to stop the air conditioner 10.

15 Moreover, the status parameter  $A_i$  on the apparatus status database  $3C_3$  is turned off (step 501). If the air conditioner 10 is now not operated ( $A_i \neq ON$  in step 500), similarly the air conditioner 10 is turned on, and the status parameter  $A_i$  on the apparatus status

20 database  $3C_3$  is turned on (step 502).

Thus, each time the A-button 4a of remote controller 4 is single-clicked under the condition that the air conditioner 10 is designated by the pointer 7, the air conditioner 10 is repeatedly started to operate

25 and stop.

④ of step 107 in FIG. 9; i.e., the case when the pointer 7 is within the apparatus recognition range  $AR_{10}$  (FIG. 6B) of air conditioner 10, and when the A-

button 4a is double clicked on the remote controller 4:

This case corresponds to the operation shown in FIG. 16. In this case, control is performed according to the flowchart of FIG. 17.

- 5           That is, the user half-pushes the A-button 4a with the remote controller 4 directed to the air conditioner 10 so that the laser beam is applied as pointer 7 to the air conditioner 10 as shown in FIG. 16A, and the A-button 4a of remote controller 4 is
- 10 double clicked as shown in FIG. 16B. At this time, the personal computer 3c detects that the coordinate position of the pointer 7 within the controllable region 6 is within the apparatus recognition range  $AR_{10}$  of air conditioner 10. If the status parameter  $A_i$  of the air
- 15 conditioner 10 on the apparatus status database  $3C_3$  (see FIG. 7) is ON (i.e., if the air conditioner 10 is operating: step 600 in FIG. 17), the routine goes directly to step 602 in FIG. 17. If this status parameter  $A_i$  is OFF (i.e., if the air conditioner 10 is
- 20 at a halt), the personal computer 3c energizes the relay 16a (FIG. 5) to make the air conditioner 10 operative, so that the status parameter  $A_i$  on the apparatus status database  $3C_3$  is turned ON (step 601 in FIG. 17), and the processing goes to step 602.
- 25           In step 602, as shown in FIG. 16B, the personal computer 3c reads from the storage portion 3C the image of operation panel 22 of the air conditioner as shown in FIG. 16C, and supplies it to the projector

10082107.022602

2, permitting the projector 2 to display the panel 22 as shown in FIG. 16C. Although the displaying of operation panel 22 is performed by the projector 2 (FIG. 1), this operation panel 22 does not include the same color as the laser beam. Therefore, the image of operation panel 1a does not appear on the light-sensitive screen of the video camera 1 with the band-pass filter 1a mounted.

This operation panel 22 has icons 22a of setting items such as "airflow", "temperature", "timer" and "operation" horizontally arranged, and marks "△" 22b, "▽" 22c on the top and bottom of each icon 22a as shown in FIG. 16F. This operation panel 22 is displayed on the surface of a wall 23 near the air conditioner 10. Any one of these setting icons 22a and its associated marks "△" 22b, "▽" 22c are designated by the pointer 7, so that the operation of the air conditioner 10 can be controlled for each selected setting item.

When, for example, timer setting is tried to make, the pointer 7 is matched to the icon 22a of "timer", thus selecting the "timer" setting item (step 603 in FIG. 17) as shown in FIG. 16C. Then, when the duration is tried to increase, the pointer 7 is matched to the mark "△" on the top of the icon 22a of "timer" and left as it is as shown in FIG. 16D. At this time, the setting time is stepwise increased by a predetermined time, for example, one minute at a time (step 605

10002107-022602

in FIG. 17). When the setting time of the timer is tried to decrease, the pointer 7 is matched to the mark "▽" on the bottom of the icon 22a of "timer", thereby making the setting time be stepwise decreased by, for example, one minute at a time (step 606 in FIG. 17).

After the above operation, the processing goes back to step 603 where control can be again made for another setting item. When the A-button 4a is double clicked (step 607 in FIG. 17) under the condition that the pointer 7 is placed at any position on the operation panel 22 as shown in FIG. 16E, the setting control for the air conditioner 10 is finished, and the processing goes back to step 104 in FIG. 9.

Thus, the user can turn the air conditioner 10 on and off or set desired operation items while sitting on a sofa. In addition, since such setting operations can be performed by pointing with the visible laser beam the operation panel 22 that is magnified and displayed on the air conditioner 10 to be controlled or on a wall, the user can operate easily without mistake.

[Remote controlling of TV set 9]

⑤ of step 107 in FIG. 19; i.e., the case when the pointer 7 is within the apparatus recognition range AR<sub>3</sub> (FIG. 6B) of TV set 9, and when the A-button 4a is single-clicked on the remote controller 4:

In this case, control is made according to the flowchart of FIG. 18.

That is, the user half-pushed the A-button 4a with the remote controller 4 directed to the TV set 9 so that the laser beam can be applied as the pointer 7 to the TV set 9, and the A-button 4a of remote controller 4 is once full-pushed, or single-clicked. When the personal computer 3c of control box 3 detects from the output of the video camera 1 that this pointer 7 is within the apparatus recognition range AR<sub>9</sub> of TV set 9, it checks the status parameter Te of TV set 9 on the basis of the apparatus status database 3C<sub>3</sub> in the storage portion 3C (see FIG. 7) (step 700 in FIG. 18). If Te = ON, the TV set 9 is decided to be in the on-state, and a control signal is transmitted to the TV set 9, energizing the relay 16d (see FIG. 5) to switch the TV set 9 off. Moreover, the status parameter Te on the apparatus status database 3C<sub>3</sub> is turned OFF (step 701). If the TV set 9 is off (Te ≠ ON in step 700 in FIG. 17), similarly the TV set 9 is turned on, and the status parameter Te on the apparatus status database 3C<sub>3</sub> is turned ON (step 702 in FIG. 18).

Thus, each time the A-button 4a of remote controller 4 is single-clicked under the condition that the TV set 9 is designated by the pointer 7, the TV set 9 can be repeatedly started to be turned on and off.

Here, when the TV set 9 is in the on-state, the pointer 7 is applied to the TV set 9, and the A-button 4a is double clicked, thereby causing the operation panel of TV set 9 to be displayed so that the



setting items such as channel and sound volume can be changed as in the case of air conditioner 10. The operation panel may be displayed on the surface of a wall near the TV set 9 or superimposed on a program displayed on the screen of TV set 9. When the pointer 7 is matched to the displayed operation panel, and the A-button 4a is double clicked, the operation panel disappears.

⑥ of step 107 in FIG. 9; i.e., the case when the pointer 7 is within the apparatus recognition range  $AR_9$  (FIG. 6B) of the TV set 9, and when the A-button 4a is double clicked on the remote controller 4:

In this case, the TV set 9 is controlled according to the flowchart of FIG. 19.

That is, the user half-pushes the A-button 4a with the remote controller 4 directed to the TV set so that the laser beam can be applied as the pointer 7 to the TV set 9, and the A-button 4a of remote controller 4 is double clicked. At this time, the personal computer 3c detects that the coordinate position of the pointer 7 within the controllable region 6 is within the apparatus recognition range  $AR_9$  of TV set 9. If the status parameter  $Te$  of this TV set 9 on the apparatus status database  $3C_3$  (FIG. 7) is ON (i.e., if TV set 9 is in the on-state: step 800), the processing goes directly to step 802. If this status parameter  $Te$  is OFF (i.e., the TV set 9 is in the off-state), the personal computer 3c energizes the relay 16d (FIG. 5),

10000107.022602

thereby switching TV set 9 on, and the processing goes to step 802.

At this time, when both refrigerator 8 and electronic oven 13 are not designated, the operation panel of TV set 9 is displayed as described above. In addition, when the A-button 4a of remote controller 4 is double clicked under the same state, the processing goes through steps 802, 804 back to the step 104 in FIG. 9, and the TV set 9 is only maintained in the on-state.

Here, in steps 105 - 107 in FIG. 9, in the case of

⑦ of step 107; i.e., when the B-button 4b (see FIG. 4) of remote controller 4 is full-pushed, or single-clicked under the condition that the pointer 7 is within the apparatus recognition range  $AR_8$  (FIG. 6B) of refrigerator 8, the refrigerator 8 is decided to be designated, and thus the status parameter  $Re$  of the refrigerator 8 is ON on the apparatus status database 3C<sub>3</sub> in the storage portion 3C of control box 3 as shown in FIG. 20. Thus, the refrigerator 8 is in the state in which it is specified.

Similarly, in the case of

⑧ of step 107; i.e., when the B-button 4b (see FIG. 4) of remote controller 4 is full-pushed, or single-pushed on the remote controller 4 under the condition that the pointer 7 is within the apparatus recognition range  $AR_{13}$  (FIG. 6B) of electronic oven 13,

10002107.022602

the electronic oven 13 is decided to be designated, and the status parameter Mi for the electronic oven 13 is ON on the apparatus status database 3C, in the storage portion 3C of control box 3 as shown in FIG. 21.

- 5 Hence, the electronic oven 13 is shown to be in the specified state.

Thus, as shown in FIG. 22A, the refrigerator 8 is pointed by the pointer 7, and the B-button 4b of remote controller 4 is single-clicked to specify the refrigerator 8. Under this condition, as shown in FIG. 22B, the A-button 4a of remote controller 4 is double clicked while the pointer 7 is being applied to TV set 9; thereby switching the TV set 9 on (step 800) as in FIG. 19 or the TV set 9 is turned on (step 801) as shown in FIG. 19. At this time, the personal computer 3c detects, if the refrigerator 8 and electronic oven 13 are designated, from the status parameters Re, Mi on the apparatus status database 3C, in the storage portion 3C. The result is that Re = ON, and that Mi = OFF, i.e., only the refrigerator 8 is decided to be specified.

Here, at the time of the initial status setting (step 101) in FIG. 9, the information (list of foods and drinks as recipe ingredients placed ) within refrigerator 8 is read out by the control box 3 and stored in the storage portion 3C. In addition, for example, means for registering foods is provided for this refrigerator 8. When the user takes foods and

10082107.022602

drinks in and out of the refrigerator 8 for recipe ingredients, the names of the ingredients are registered by this means. This registering means may be input means such as a keyboard, so that when the user takes ingredients in and out, the names thereof are entered by this means. Or a barcode sensor may be provided to read out the barcodes of the names attached to the purchased foods.

In the refrigerator 8 is provided means for managing the foods and drinks to be taken in and out. This managing means modifies the list of products contained when foods and/or drinks are taken in or out.

Turning back to FIG. 19, when only the refrigerator 8 is specified by the user who operates as shown in FIG. 22A, the status parameters are found as Re = ON, and Mi = OFF (step 802). Thus, when the A-button 4a of remote controller 4 is double clicked while the pointer 7 is being applied to the TV set 9 as shown in FIG. 22B, the personal computer 3c reads out foods information of refrigerator 8 from the storage portion 3C, and as shown in FIG. 23B, it causes information 25 within refrigerator 8 to be displayed on the TV set 9 that is also displaying a broadcast program 24 as shown in FIG. 23A. Also, the personal computer 3c initializes the status parameter Re for specifying refrigerator 8 to be OFF on the apparatus status database 3C, in the storage portion 3C (step 803 in FIG. 19).

Thus, the user can see the foods placed in the refrigerator 8 from the display screen of TV set 9.

Moreover, as shown in FIG. 24A, the refrigerator 8 is designated by the same operation as in FIG. 22A, and as shown in FIG. 24B, the electronic oven 13 is also specified by single-clicking the B-button 4b of remote controller 4. Then, as shown in FIG. 24C, the A-button 4a is double clicked on the TV set 9 same as in FIG. 22B. At this time, Re = ON, and Mi = ON. This means that both the refrigerator 8 and electronic oven 13 have been designated (step 804 in FIG. 19). The possible recipes using current foods placed in refrigerator 8 are searched according to, for example, recorded cooking programs that were broadcast so far or received through Internet, and the resulting information 26 about recipe is displayed on TV set 9 as shown in FIG. 23C. Then, the personal computer 3c initializes the status parameters Re, Mi for specifying refrigerator 8 and electronic oven 13 on the apparatus status database 3C, of storage portion 3C to be OFF (step 805 in FIG. 19).

When the A-button 4a of remote controller 4 is double clicked under the condition that the pointer 7 is within the apparatus recognition range AR, (FIG. 6B) of the TV set 9, and in this case when the electronic oven 13 as well as refrigerator 8 is already specified, the information of recipe is immediately displayed as shown in FIG. 23C through steps 802 and

804. In this case, under the condition that the information 25 of foods placed in the refrigerator 8 is displayed (step 803 in FIG. 19) as shown in FIG. 23B, when the electronic oven 13 is designated as shown in 5 FIG. 24B, the routine goes from step 803 through step 804 to step 805, where the information 26 of recipe is displayed as shown in FIG. 23C.

In addition, under the condition that the list of foods placed in the refrigerator 8 is displayed 10 (step 803 in FIG. 19) as shown in FIG. 23B or that the recipe information is displayed (step 805 in FIG. 19) as shown in FIG. 23C, the A-button 4a of remote controller 4 is double clicked with the pointer 7 matched to TV set 9, and at this time the processing goes back 15 to step 104 in FIG. 9.  
[Displaying other items]

⑨ of step 107 in FIG. 9; i.e., the case when the A-button 4a of remote controller 4 is double clicked under the condition that the pointer 7 is 20 placed within other region than apparatus recognition ranges  $AR_8 \sim AR_{11}$ ,  $AR_{13}$  of controlable range 6:

In this case, control is made according to the flowchart shown in FIG. 25.

That is, when the A-button 4a of remote 25 controller 4 is double clicked under the condition that the pointer 7 is placed within other region than the apparatus recognition ranges  $AR_8 \sim AR_{11}$ ,  $AR_{13}$  of controlable range 6, the personal computer 3c reads

information 27 of room property (attribute) shown in  
FIG. 26A from the storage portion 3C, and supplies it  
to the projector 2. The projector 2 projects this  
information image 27 on a predetermined place of the  
5 wall surface 23 as shown in FIG. 26B. This room  
property is, for example, the locked situations of each  
room, the state in which each room is powered or not,  
information of received e-mails and current situation  
of family members. This room property information is  
10 supplied from each monitor to the personal computer 3c,  
and stored in the storage portion 3C (step 1100 in FIG.  
25).

Under this situation, when the A-button 4a is  
again double clicked, the displaying is finished, and  
15 the processing goes back to step 104 in FIG. 9 (step  
1104 in FIG. 25).

The room property information 27 displayed  
shown in FIG. 26A includes a menu for selecting "TV  
program", "weather conditions", "security check" and  
20 "room property". Under this condition shown in FIG.  
26B, the A-button 4a is single-clicked with the pointer  
7 matched to one of the items (here, "TV program"),  
thus selecting it (step 1101 in FIG. 25). Also, while  
the A-button 4a is being half-pushed, the remote  
25 controller 4 is moved so that a locus 28 is depicted by  
pointer 7 on a certain area of wall 23, and the A-  
button 4a is single-clicked (step 1102 in FIG. 25).  
Thus, a rectangular region 29 substantially

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corresponding to the depicted locus 28 is set up. Within this region 29, is projected and displayed a television program of a certain channel by the projector 2 as shown in FIG. 26C. This TV program is  
5 received by a separately provided television receiver. This received video signal is supplied to the projector 2 under the control of personal computer 3c. This region 29 also includes an operation panel (not shown) on which the received channel and sound volume can be  
10 changed when the A-button 4a is single clicked with the pointer 7 matched to a proper point (step 1103).

When the A-button 4a is double clicked under the condition that the pointer 7 is placed on the wall surface 27 and that the TV program is displayed, the  
15 displaying is finished, and the processing goes back to step 104 in FIG. 9.

Thus, in this embodiment, desired information can be displayed by simple operation of pointer on the surface of wall 23.

20 In FIG. 9, when the apparatus in the room are not controlled with the remote controller 4 and the room is not in a controlled state, the condition of step 104 is brought about. In this condition, when the system of this embodiment is stopped by operating the  
25 above main switch, each appliance is returned back to the initial state (step 108).

Thus, according to this embodiment, the electric appliances can be remotely controlled by only

10082107-022602



directing the pointer 7 to the associated one of the appliances. Since this pointer is displayed to be visible, the associated appliance can be designated by very easy operation without mistake. In addition,  
5 since different appliances can be remotely controlled by the common operation method, the remote controller can be constructed to be simple and the operation thereof is also simple.

If the user sets the pointer 7 on the surface  
10 of the associated appliance, this pointer 7 is sure to be placed within the apparatus recognition range for this appliance. Thus, under this condition, the above remote control operations can be made by clicking the A-button 4a and B-button 4b of remote controller 4.

15 Also, when the control mode is decided by the movement of pointer 7 as in the control of lamp 11, the apparatus recognition range of electric appliances is required to be set wider to some degree than the actual surface of the appliance. Thus, in the dimming mode of  
20 lamp 11 as, for example, shown in FIG. 11B, even when the pointer 7 is not on the surface of lamp 11, but out of the surface, the pointer 7 is moved up and down, thereby making the brightness of lamp 11 increase or decrease. This operation can be similarly made for  
25 other appliances. Moreover, in this embodiment, even when more than two appliances of the same type, such as two lamps 11, are provided, these appliances can be separately remotely controlled by setting the apparatus

recognition range for each one.

5 In addition, while the remote controller emits a visible laser beam for pointer 7 that points to an electric appliance in this embodiment, the remote controller may emit a directional electromagnetic wave including a non-visible laser beam, in which case a sheet-like substance that emits visible light of a particular wavelength is attached on a certain part of each appliance or wall and excited by this electro-  
10 magnetic wave. Thus, when this electromagnetic wave is irradiated from the remote controller to the sheet-like substance, a visible pointer appears on this irradiated region.

Also, while all the electric appliances to  
15 be controlled are installed within the field of view 6 of video camera 1 in this embodiment, the apparatus recognition ranges for the appliances to be controlled may be within the field of view 6 of video camera 1. Even in this case, these appliances can be remotely  
20 controlled. If the refrigerator 8, for example, is provided in another room and thus not placed within the field of view 6 of video camera 1 unlike the scene in FIG. 1, provided that the apparatus recognition range  $AR_8$  for this refrigerator 1 is set within the field view  
25 6 of video camera 1, the pointer 7 is used to point to this apparatus recognition range  $AR_8$ , thereby designating this refrigerator 8. The setting of the apparatus recognition range is made by the user's operation using

the pointer as described previously. Thus, the place in which the apparatus recognition range is set is not required to be coincident with the place where the associated appliance is installed. However, since the user cannot view this apparatus recognition range, any mark is placed at the set position, a pamphlet for the guide is previously produced or the user points to the wall surface by the pointer so that the pointed region is detected to be within the apparatus recognition range by the control box 3 from the output from the video camera 1. At this time, the control box 3 causes the projector to project and display the image of an appliance out of the field of view 6 or operation panel at the place, thus informing the user.

Thus, according to the invention, electric appliances of different types can be simply controlled by simple operation, and the appliance to be controlled can be selected by a simple method. The operability can be improved to a great extent.

It should be further understood by those skilled in the art that the foregoing description has been made on embodiments of the invention and that various changes and modifications may be made in the invention without departing from the spirit of the invention and the scope of the appended claims.